



DFK 33UR0234

Technical Reference Manual



1. Quick Facts	5
2. Dimensional Diagrams	7
2.1 DFK 33UR0234 C-Mount with Tripod Adapter	7
2.2 DFK 33UR0234 C-Mount without Tripod Adapter	8
2.3 DFK 33UR0234 CS-Mount with Tripod Adapter	9
2.4 DFK 33UR0234 CS-Mount without Tripod Adapter	10
3. I/O Connector	11
3.1 12-pin I/O Connector	11
3.1.1 TRIGGER_IN	12
3.1.2 STROBE_OUT	12
4. Spectral Characteristics	13
4.1 IR-Cut Filter	13
4.2 Spectral Sensitivity - AR0234CS	13
5. Camera Controls	14
5.1 Sensor Readout Control	14
5.1.1 Pixel Format	14
5.1.1.1 8-Bit Bayer Raw	15
5.1.1.2 10-Bit Packed Bayer Raw	15
5.1.1.3 16-Bit Bayer Raw	15
5.1.1.4 YUV 4:2:2	16
5.1.1.5 YUV 4:1:1	16
5.1.1.6 RGB24	16
5.1.1.7 8-Bit Monochrome	17
5.1.2 Resolution	17
5.1.3 Readout Modes	18
5.1.4 Frame Rate	19
5.1.5 Partial Scan Offset	21
5.1.6 Image Flipping	23
5.2 Image Sensor Control	23
5.2.1 Exposure Time	23
5.2.2 Gain	24
5.2.3 Black Level	24
5.3 Automatic Exposure and Gain Control	24
5.3.1 Auto Exposure	25
5.3.2 Auto Gain	25
5.3.3 Auto Reference Value	25
5.3.4 Highlight Reduction	26
5.3.5 Auto Exposure Limits	26
5.3.6 Auto Gain Limits	27
5.4 Trigger	28



5.4.1	Trigger Mode	28
5.4.2	Trigger Polarity	28
5.4.3	Software Trigger	29
5.4.4	Trigger Burst Count	29
5.4.5	Trigger Source	30
5.4.6	Trigger Overlap	30
5.4.7	Trigger Delay	30
5.5	Trigger Timing Parameters	31
5.5.1	Trigger Debounce Time	31
5.5.2	Trigger Mask Time	31
5.5.3	Trigger Noise Suppression Time	32
5.6	Digital I/O	32
5.6.1	General Purpose Input	32
5.6.2	General Purpose Output	33
5.7	Strobe	33
5.7.1	Strobe Enable	33
5.7.2	Strobe Polarity	34
5.7.3	Strobe Operation	34
5.8	White Balance	35
5.8.1	Auto White Balance	35
5.8.2	White Balance Mode	35
5.8.3	Manual White Balance	36
5.9	Image Processing	38
5.9.1	Gamma	38
5.9.2	Lookup Table	39
5.10	Color Processing	40
5.10.1	Hue	40
5.10.2	Saturation	41
5.11	Region of Interest for Auto Functions	41
5.11.1	Auto Functions ROI Enable	41
5.11.2	Auto Functions ROI Preset	42
5.11.3	Auto Functions ROI Custom Rectangle	42
5.12	User Sets	44
5.12.1	User Set Selector	44
5.12.2	Load User Set	44
5.12.3	Save User Set	45
5.12.4	Default User Set	45
5.13	Timestamp Control	45
5.13.1	Timestamp Latch	45
5.13.2	Timestamp Latch Value	46
5.13.3	Timestamp Reset	46
5.14	Events	46
5.14.1	Event Selector	46



5.14.2	Event Notification	47
5.14.3	Event Exposure End	47
5.14.4	Event Frame Trigger Missed	48
5.14.5	Event Line1 Falling Edge	48
5.14.6	Event Line1 Rising Edge	49
5.14.7	Event Test	49
5.15	Bandwidth Control	50
5.15.1	Device Link Throughput Limit Mode	50
5.15.2	Device Link Throughput Limit	51
6.	Revision History	52

1 Quick Facts

General	
Vision Standard	USB3 Vision
Dynamic Range	10 bit
Resolution	1920x1200
Frame Rate at Full Resolution	100
Pixel Formats	8-Bit Monochrome 8-Bit Bayer (GR) 10-Bit Bayer Packed (GR) 16-Bit Bayer (GR) RGB24 YUV 4:2:2 YUV 4:1:1

Optical Interface	
IR-Cut filter	Yes
Sensor Type	onsemi AR0234CS
Shutter Type	Global
Sensor Format	1/2.6 inch
Pixel Size	3.0 μm
Lens Mount	C/CS

Electrical Interface	
Interface	USB 3.0
Supply Voltage	4.75 VDC to 5.25 VDC
Current Consumption	approx 600 mA @ 5 VDC
I/O Connector	12-pin connector for trigger and strobe or general purpose input/output

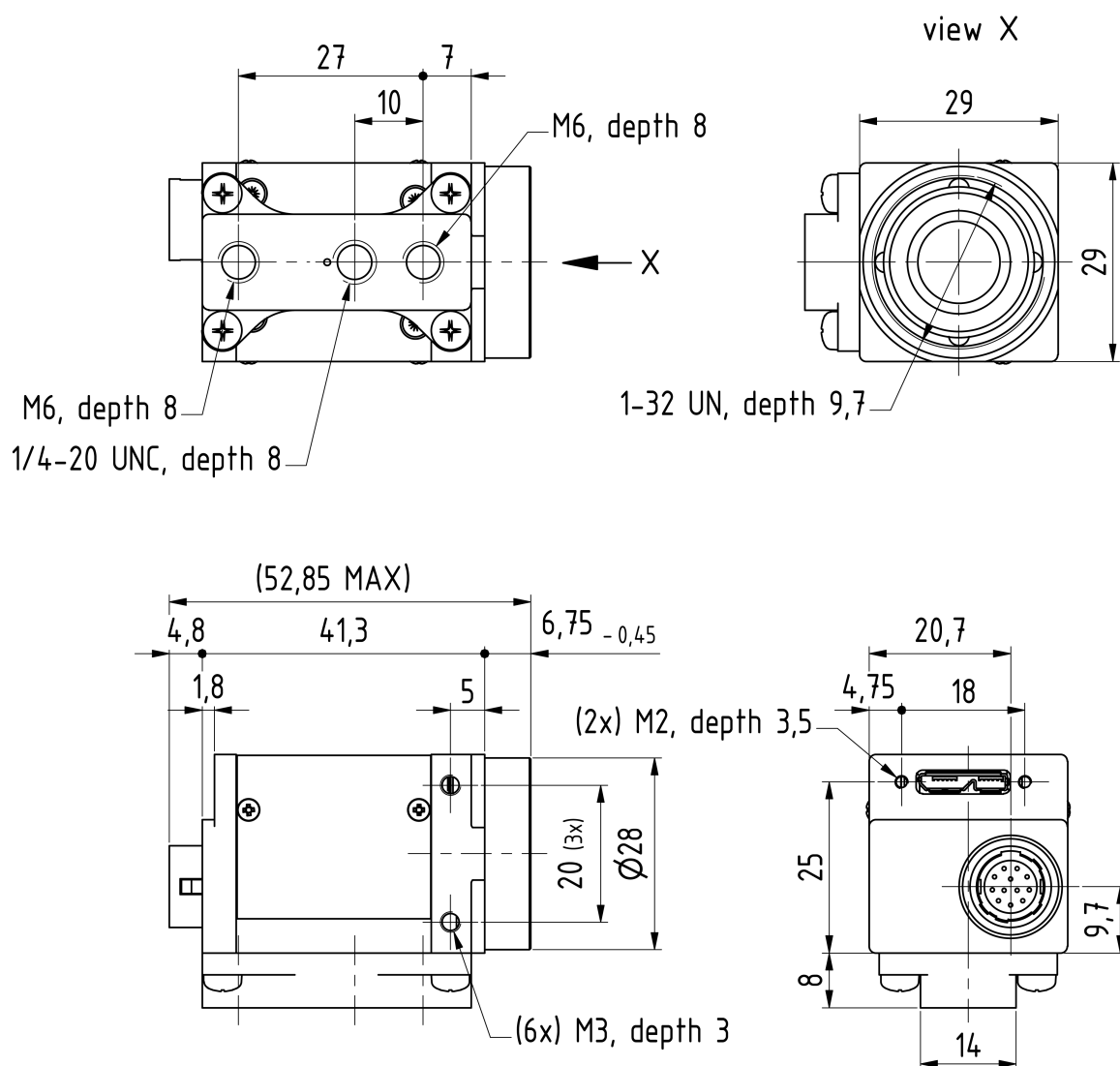
Mechanical Data	
Dimensions	H: 29 mm, W: 29 mm, L: 43 mm
Mass	65 g

Adjustments	
Shutter	50 μ s to 0.25 s
Gain	0 dB to 42,14 dB

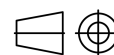
Environmental Conditions	
Housing Temperature (operating)	-5 °C to 50 °C
Temperature (storage)	-20 °C to 80 °C
Humidity (operating)	20 % to 80 % (non-condensing)
Humidity (storage)	20 % to 95 % (non-condensing)

2 Dimensional Diagrams

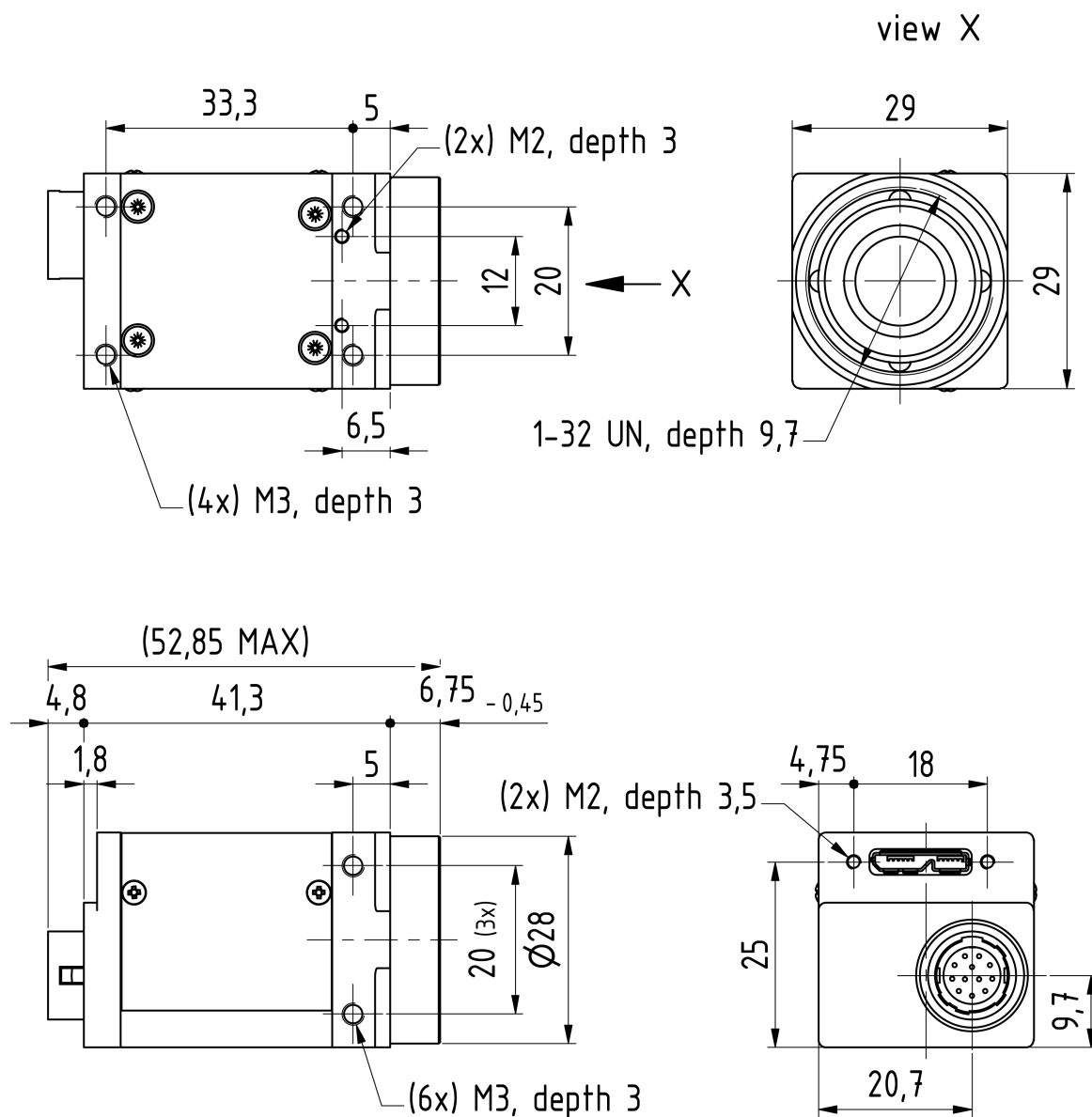
2.1 DFK 33UR0234 C-Mount with Tripod Adapter



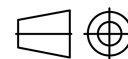
Dimensions: mm
Tolerances: DIN ISO 2768-f



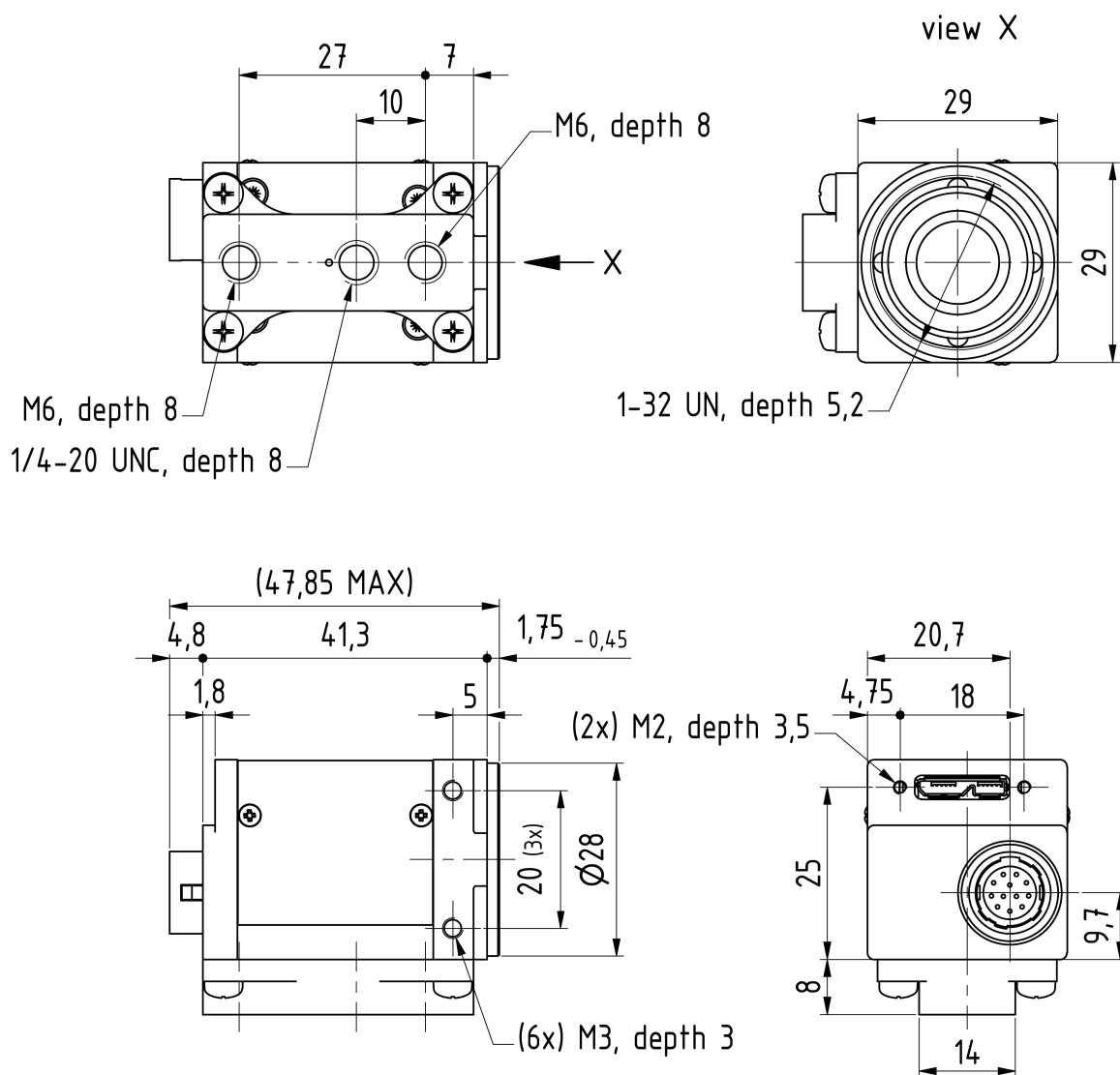
2.2 DFK 33UR0234 C-Mount without Tripod Adapter



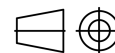
Dimensions: mm
Tolerances: DIN ISO 2768-f



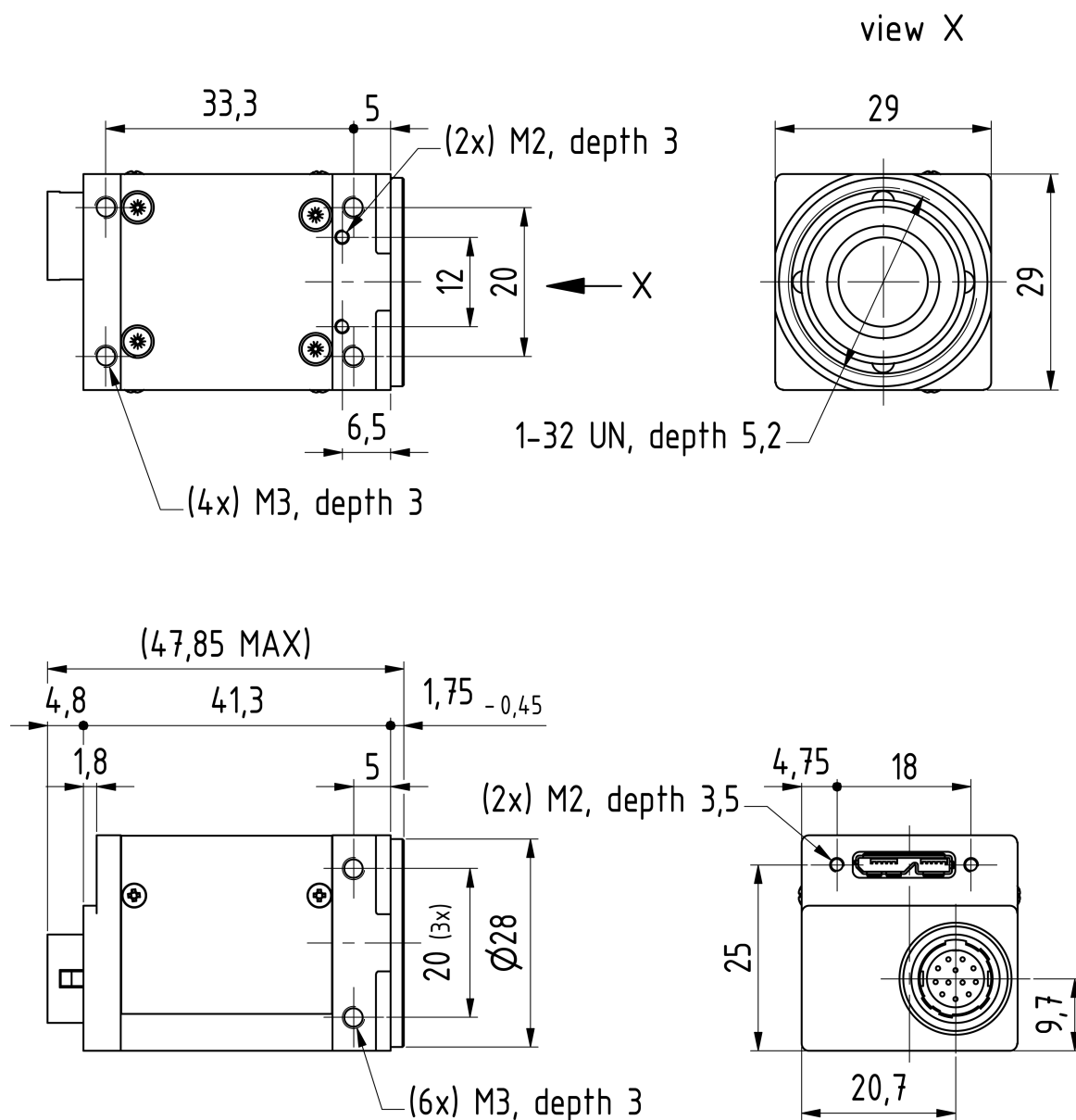
2.3 DFK 33UR0234 CS-Mount with Tripod Adapter



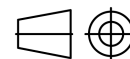
Dimensions: mm
Tolerances: DIN ISO 2768-f



2.4 DFK 33UR0234 CS-Mount without Tripod Adapter

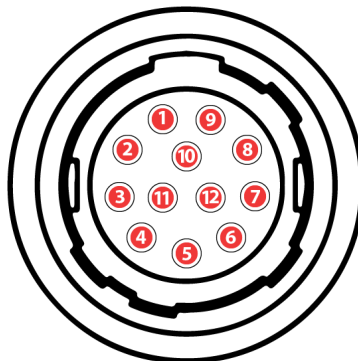


Dimensions: mm
Tolerances: DIN ISO 2768-f



3 I/O Connector

3.1 12-pin I/O Connector



Rear view of camera

Pin	Signal	I/O	Remarks	Characteristics			
				Min	Typ	Max	Unit
1	do not use		-	-	-	-	-
2	do not use		-	-	-	-	-
3	n.c.		-	-	-	-	-
4	n.c.		-	-	-	-	-
5	n.c.		-	-	-	-	-
6	n.c.		-	-	-	-	-
7	GND_I/O	G ³	External Ground	-	-	-	-
8	n.c.		-	-	-	-	-
9	n.c.		-	-	-	-	-
10	STROBE_OUT	O ³	Open drain	-	-	24.0 ¹	V
11	TRIGGER_IN (+)	I ³	Optocoupler signal	3.3 ²	-	24.0 ²	V
12	TRIGGER_IN (-)	I ³	Optocoupler ground	-	-	-	-

¹ max. 0.2A (ID) for open drain MOSFET!

² min. 3.5 mA driver strength required!

³ G: Ground O: Output I: Input

The part number of this Hirose connector is HR10A10R-12P(73). To create an I/O cable you need a Hirose connector HR10A-10P-12S(73).



3.1.1 TRIGGER_IN

The *TRIGGER_IN* line can be used to synchronize the start of the exposure time with external events. The [Trigger](#) section describes in detail how the image sensor's behavior can be controlled.

The current input signal can also be read directly through the [General Purpose Input](#) feature.

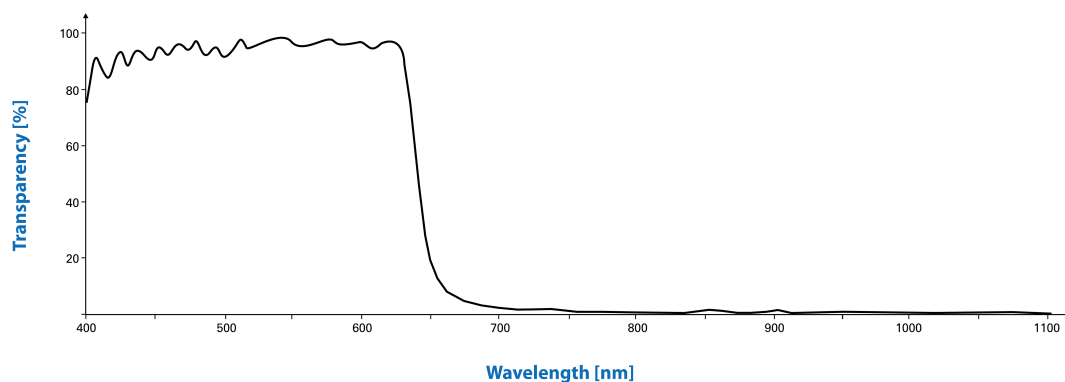
3.1.2 STROBE_OUT

The *STROBE_OUT* line's main usage is to indicate the integration time of the image sensor which allows flashes, strobes or other light sources to be synchronized with camera operation. The line's behavior can be controlled through the [Strobe](#) controls.

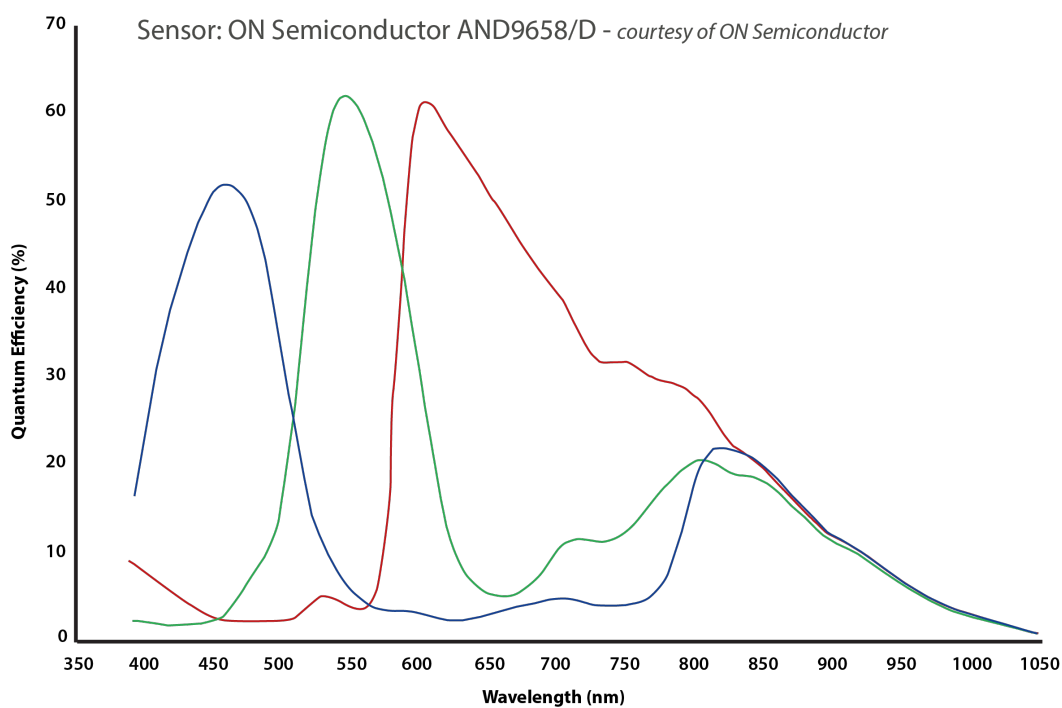
The output signal can also be directly controlled through the [General Purpose Output](#) feature.

4 Spectral Characteristics

4.1 IR-Cut Filter



4.2 Spectral Sensitivity - AR0234CS





5 Camera Controls

This section describes the parameters available for the DFK 33UR0234 camera.

The actual name of the parameter depends on the driver technology used to access the camera. Parameter names are listed for the most common ways to access the cameras:

- *USB3 Vision (IC Imaging Control 4, or via 3rd party driver)*
- *UVC/V4L2 (on Linux, via uvcvideo)*
- *IC Imaging Control 3.x (on Windows, via Device Driver for The Imaging Source USB 33U, 37U and 38U Cameras)*

Please note: When the camera is connected to a USB2 controller and used in V4L2 mode or by *IC Imaging Control 3.x*, read requests can lead to frame drops. Avoid reading camera features to ensure a stable image transmission.

5.1 Sensor Readout Control

5.1.1 Pixel Format

The pixel format defines the data type of the pixels transmitted to the computer. The bits per pixel needed for a particular pixel format influence the required bandwidth.

The driver technology used to access the camera significantly impacts the way the pixel format is controlled:

- When using *IC Imaging Control 4* or *USB3 Vision*, the pixel format is controlled through the `PixelFormat GenICam` feature.
- When using the `uvcvideo` driver on Linux, the pixel format is defined by `video4linux2`.
- When using *IC Imaging Control 3.x*, the pixel format is part of the video format - a parameter which combines pixel format, resolution and readout mode. For more information, refer to the *IC Imaging Control 3.x* documentation sections on `VideoFormat` and `VideoFormatDesc`.

The DFK 33UR0234 color camera supports multiple pixel formats with variable bits-per-pixel settings. The names of the pixel formats and the way to select them depends on the driver used to control the camera. The following table contains a short overview of all possible formats followed by a more detailed description.

Pixel Format	Bits Per Pixel	USB3 Vision	UVC	TIS UVC Driver
8-Bit Bayer (GR)	8	BayerGR8	GRBG	RGB32, Y800
10-Bit Packed Bayer (GR)	10	BayerGR10p	GRAp	RGB64, Y16
16-Bit Bayer (GR)	16	BayerGR16	GR16	RGB64, Y16
YUV 4:2:2	16	YCbCr422_8	YUY2	YUY2
YUV 4:1:1 (a)	12	YCbCr411_8		
YUV 4:1:1 (b)	12	YCbCr411_8_CbYYCrYY	Y411	Y411
RGB24	24	BGR8	RGB24	RGB24
8-Bit Monochrome	8	Mono8		

5.1.1.1 8-Bit Bayer Raw

This format transmits data using one byte for each pixel.

USB3 Vision drivers see this pixel format as one of the 8-bit bayer raw formats (BayerGR8, BayerRG8, BayerGB8, BayerBG8).

UVC drivers see it with the *FourCC* GRBG, RGGB, GBRG or BA81.

The *Device Driver for The Imaging Source USB 33U, 37U and 38U Cameras* simplifies this variety of possible pixel formats and offers two video formats instead: RGB32 and Y800. The RGB32 format results from the driver's automatic debayering of the raw image data, while the Y800 format contains the raw data which is reinterpreted as monochrome.

5.1.1.2 10-Bit Packed Bayer Raw

This format transmits data using 5 bytes for each group of 4 consecutive pixels.

USB3 Vision drivers see this pixel format as one of the 10-bit packed bayer raw formats (BayerGR10p, BayerRG10p, BayerGB10p, BayerBG10p).

UVC drivers see it with the *FourCC* GRAp, RGAp, GBAp or BGAp.

The *Device Driver for The Imaging Source USB 33U, 37U and 38U Cameras* simplifies this variety of possible pixel formats and offers two video formats instead: RGB64 and Y16. The RGB64 format results from the driver's automatic debayering of the raw image data, while the Y16 format contains the raw data which is reinterpreted as monochrome. Since the DFK 33UR0234 camera offers both 10-bit packed and 16-bit bayer raw pixel formats, the driver uses the 10-bit packed format when the RGB64 or Y16 video format is selected.

5.1.1.3 16-Bit Bayer Raw

This format transmits data using 2 bytes for each pixel.



The sensor of the DFK 33UR0234 camera is not able to provide 16-bit data output. The pixel data is transmitted in the most significant bits. This allows application programs to ignore the sensor-specific data type and to treat the data as if the sensor outputs 16 bits.

USB3 Vision drivers see this pixel format as one of the 16-bit packed bayer raw formats (BayerGR16, BayerRG16, BayerGB16, BayerBG16).

UVC drivers see it with the *FourCC* GR16, RG16, GB16 or BA16.

The *Device Driver for The Imaging Source USB 33U, 37U and 38U Cameras* simplifies this variety of possible pixel formats and offers two video formats instead: RGB64 and Y16. The RGB64 format results from the driver's automatic debayering the raw image data, while the Y16 format contains the raw data which is reinterpreted as monochrome.

5.1.1.4 YUV 4:2:2

This format transmits an 8-bit luminance value for every pixel and a pair of chrominance values for every two pixels.

The camera converts the raw pixel data from the sensor to YUV 4:2:2. Since YUV 4:2:2 averages to 2 bytes per pixel, the YUV 4:2:2 pixel format requires two times the bandwidth of the 8-bit raw format, thus reducing the maximum possible frame rate.

USB3 Vision drivers see this pixel format as YCbCr422_8.

UVC drivers see it with the *FourCC* YUY2.

The *Device Driver for The Imaging Source USB 33U, 37U and 38U Cameras* offers this pixel format as the YUY2 video format.

5.1.1.5 YUV 4:1:1

This format transmits an 8-bit luminance value for every pixel and a pair of chrominance values for every four pixels.

The two YUV 4:1:1 pixel formats only differ in their byte order.

The camera converts the raw pixel data from the sensor to YUV 4:2:2. Since YUV 4:2:2 averages to 1.5 bytes per pixel, the YUV 4:2:2 pixel format requires two 50% more bandwidth than the 8-bit raw format, thus reducing the maximum possible frame rate.

USB3 Vision drivers see this pixel format as YCbCr411_8 and YCbCr411_8_CbYYCrYY.

UVC drivers see it with the *FourCC* Y411.

The *Device Driver for The Imaging Source USB 33U, 37U and 38U Cameras* offers this pixel format as the Y411 video format.

5.1.1.6 RGB24

The camera converts the raw pixel data from the sensor to RGB24. Since RGB24 uses 3 bytes to store 1 pixel, the RGB24 pixel format requires three times the bandwidth of the 8-bit raw format, thus reducing the maximum possible frame rate.

USB3 Vision drivers enumerate this pixel format as BGR8.

UVC drivers see it with the *FourCC* `RGB24`.

The *Device Driver for The Imaging Source USB 33U, 37U and 38U Cameras* enumerates this pixel format as the `RGB24` video format.

5.1.1.7 8-Bit Monochrome

The camera generates the pixel data by debayering the raw pixel data and transmitting only the luminance information.

USB3 Vision drivers enumerate this pixel format as `Mono8`.

UVC drivers do not have access to this format.

5.1.2 Resolution

The DFK 33UR0234 allows the user to specify which rectangular region of the image sensor to read out during camera operation. The size of this rectangle determines the number of pixels that have to be transferred for each frame and has a significant influence on the required USB bandwidth.

Lowering the resolution also often allows the image sensor to operate at a higher frame rate. Changes in the vertical resolution have more effect on the maximum frame rate than changes in the horizontal direction.

The way the resolution is controlled varies greatly between the driver technology used to access the camera:

- When using *USB3 Vision*, the resolution is controlled through the GenICam features Width and Height.
- When using the `uvccvideo` on Linux, the resolution is selected from a list of fixed formats. Dynamic frame sizes are not available.
- When using *IC Imaging Control*, the resolution is part of the video format, a parameter that combines pixel format, resolution and readout mode. For more information, refer to the *IC Imaging Control* documentation sections on `VideoFormat` and `VideoFormatDesc`.

Parameter	Horizontal Resolution
Minimum	256
Maximum	1920
Increment	16
USB3 Vision: GenICam	Width
Type	Integer

Parameter	Vertical Resolution
Minimum	16
Maximum	1200
Increment	2
USB3 Vision: GenICam	Height
Type	Integer

5.1.3 Readout Modes

The DFK 33UR0234 camera offers different sensor readout modes.

By default, the camera outputs all pixels of the image sensor.

In *skipping* modes, the image sensor regularly skips a number of rows and/or columns during readout. The resulting output image is smaller but contains the same field of view than the image produced by default readout mode.

In *binning* modes, a number of neighboring pixels is merged into one output pixel during readout. The nature of this merge operation is sensor-specific, most sensors either add the pixel values or average them.

Generally, binning modes provide better image quality than skipping modes. However, skipping modes usually provide a higher maximum frame rate.

The way the readout modes are controlled depends greatly upon which driver technology is used to access the camera:

- When using *USB3 Vision*, the readout mode is controlled through the *GenICam* features `DecimationHorizontal`, `DecimationVertical`, `BinningHorizontal` and `BinningVertical`.
- When using *IC Imaging Control*, the readout mode is part of the video format - a parameter that which combines pixel format, resolution and readout mode. For more information, refer to the *IC Imaging Control* documentation sections on `VideoFormat` and `VideoFormatDesc`.

The following readout modes are supported:

- Default
- Skipping 2X
- Binning 2X

Parameter	Binning Horizontal
Valid Values	1, 2
USB3 Vision: GenICam	<code>BinningHorizontal</code>
Type	Integer

Parameter	Binning Vertical
Valid Values	1, 2
USB3 Vision: GenICam	BinningVertical
Type	Integer

Parameter	Skipping Horizontal
Valid Values	1, 2
USB3 Vision: GenICam	DecimationHorizontal
Type	Integer

Parameter	Skipping Vertical
Valid Values	1, 2
USB3 Vision: GenICam	DecimationVertical
Type	Integer

5.1.4 Frame Rate

The frame rate is specified in frames per second and determines the camera's operating speed.

The way the frame rate is controlled depends greatly upon which driver technology is used to access the camera:

- When using *USB3 Vision*, the frame rate is controlled through the *GenICam* feature `AcquisitionFrameRate`.
- When using `uvccvideo` on Linux, the frame rate is selected from a list of available frame rates.
- When using IC Imaging Control, the frame rate is selected from a list of available frame rates through APIs such as `Grabber::setFPS` or `ICImagingControl.DeviceFrameRate`.

The range of available frame rates depends upon other camera settings such as well, pixel format, resolution and readout modes.

Parameter	Frame Rate
Minimum	Depending on Pixel Format, Resolution, and Readout Mode
Maximum	Depending on Pixel Format, Resolution, and Readout Mode
USB3 Vision: GenICam	AcquisitionFrameRate
Type	Float

Please note: Enabling [Device Link Throughput Limit Mode](#) can limit the frame rate below the configured value.

The following tables show the maximum frame rate for some combinations of pixel format and resolution.

8-Bit Bayer Raw

Width	Height	Maximum Frame Rate
1920	1200	100
1920	1080	110
640	480	242

10-Bit Packed Bayer Raw

Width	Height	Maximum Frame Rate
1920	1200	100
1920	1080	110
640	480	242

16-Bit Bayer Raw

Width	Height	Maximum Frame Rate
1920	1200	81
1920	1080	90
640	480	242

YUV 4:2:2

Width	Height	Maximum Frame Rate
1920	1200	81
1920	1080	90
640	480	242

YUV 4:1:1 (a)

Width	Height	Maximum Frame Rate
1920	1200	100
1920	1080	110
640	480	242

YUV 4:1:1 (b)

Width	Height	Maximum Frame Rate
1920	1200	100
1920	1080	110
640	480	242

RGB24

Width	Height	Maximum Frame Rate
1920	1200	54
1920	1080	60
640	480	242

8-Bit Monochrome

Width	Height	Maximum Frame Rate
1920	1200	100
1920	1080	110
640	480	242

5.1.5 Partial Scan Offset

If the selected resolution is smaller than the sensor size, the part of the sensor that is actually read out can be specified by the *Partial Scan Offset X* and *Partial Scan Offset Y* parameters. By default, the camera automatically positions the offsets so that the center of the sensor is used.

Parameter	Partial Scan Offset X
Minimum	0
Maximum	1664
Increment	2
USB3 Vision: GenICam	OffsetX
Type	Integer
Video4Linux2	ROI Offset X
VCD Property	VCDID_PartialScanOffset \VCDElement_PartialScanOffsetX

Parameter	Partial Scan Offset Y
Minimum	0
Maximum	1184
Increment	2
USB3 Vision: GenICam	OffsetY
Type	Integer
Video4Linux2	ROI Offset Y
VCD Property	VCDID_PartialScanOffset \VCDElement_PartialScanOffsetY

If *Partial Scan Offset X* or *Partial Scan Offset Y* is configured to a value that would be invalid with the current setting of [Resolution](#) setting, the camera uses the maximum possible value.

Parameter	Partial Scan Auto Center
On	Automatically configure Partial Scan Offset X/Y so that the center area of the sensor is read out
True	
Off	Control Partial Scan Offset X/Y manually
False	
USB3 Vision: GenICam	OffsetAutoCenter
Type	Boolean
Video4Linux2	ROI Auto Center
VCD Property	VCDID_PartialScanOffset \VCDElement_PartialScanAutoCenter

5.1.6 Image Flipping

The DFK 33UR0234 camera allows flipping of the image data horizontally, vertically, or both. The *Flip Horizontal* and *Flip Vertical* parameters can be used to control this sensor feature.

Parameter	Flip Horizontal
True	Image data is flipped horizontally
False	Image data is not flipped horizontally
USB3 Vision: GenICam	ReverseX
Type	Boolean
Video4Linux2	Flip Horizontal
VCD Property	VCDID_FlipHorizontal\VCDElement_Value

Parameter	Flip Vertical
True	Image data is flipped vertically
False	Image data is not flipped vertically
USB3 Vision: GenICam	ReverseY
Type	Boolean
Video4Linux2	Flip Vertical
VCD Property	VCDID_FlipVertical\VCDElement_Value

5.2 Image Sensor Control

5.2.1 Exposure Time

The *Exposure Time* parameter defines the time the camera opens its (electronic) shutter when it is taking an image.

Parameter	Exposure Time
Minimum	50 μ s
Maximum	0.25 s
Default	auto
USB3 Vision: GenICam	ExposureTime
Type	Float
Video4Linux2	Exposure Time (us)
VCD Property	VCDID_Exposure\VCDElement_Value

5.2.2 Gain

The *Gain* parameter defines the amplification that is applied to the image at sensor level.

Parameter	Gain
Minimum	0 dB
Maximum	42,14 dB
Default	auto
USB3 Vision: GenICam	Gain
Type	Float
Video4Linux2	Gain (db/100)
VCD Property	VCDID_Gain\VCDElement_Value

5.2.3 Black Level

The *Black Level* parameter defines the lowest possibly intensity value of the image sensor.

Parameter	Black Level
Minimum	0
Maximum	1023
Default	42
USB3 Vision: GenICam	BlackLevel
Type	Float
Video4Linux2	Brightness
VCD Property	VCDID_Brightness\VCDElement_Value

5.3 Automatic Exposure and Gain Control

The DFK 33UR0234 camera can automatically control gain and exposure time. These automatic functions are enabled by default.

In order to optimize image parameters, a region of interest can be specified for automatic functions. Specifying a region of interest enables fine-grained control over the image area for which the image parameters are optimized. A selection of pre-defined area presets is available, but the user can also specify the coordinates of a custom rectangle.

In certain situations, it is desirable to limit the range of the auto-controlled parameters. For example, one might want to avoid high gain settings in order to keep noise levels low.

Other applications require limiting the maximum exposure time so that movements do not get blurred. Therefore, the ranges of the gain and exposure parameter can be limited.

If both auto exposure and auto gain are active, the camera tries to lower the gain value in order to reduce noise and improve the image quality.

5.3.1 Auto Exposure

Parameter	Auto Exposure
Continuous	Enable Auto Exposure
True	
Off	Disable Auto Exposure
False	
USB3 Vision: GenICam	ExposureAuto
Type	Enumeration
Video4Linux2	Auto Shutter
VCD Property	VCDID_Exposure\VCDElement_Auto

5.3.2 Auto Gain

Parameter	Auto Gain
Continuous	Enable Auto Gain
True	
Off	Disable Auto Gain
False	
USB3 Vision: GenICam	GainAuto
Type	Enumeration
Video4Linux2	Auto Gain
VCD Property	VCDID_Gain\VCDElement_Auto

5.3.3 Auto Reference Value

The *Auto Reference Value* parameter specifies the target brightness for both auto exposure and auto gain.

Parameter	Auto Reference Value
Minimum	0
Maximum	255
Default	128
USB3 Vision: GenICam	ExposureAutoReference
Type	Integer
Video4Linux2	ExposureAutoReference
VCD Property	VCDID_Exposure\VCDElement_AutoReference

5.3.4 Highlight Reduction

Enabling *Highlight Reduction* lets the auto exposure and auto gain functions reduce overexposed areas in the output image. This feature is particularly useful when using 10/12/16-bit output images and a tone mapping algorithm in post-processing when using higher bit depths as the dark areas still contain a lot of useful information.

Parameter	Highlight Reduction
True	Try to reduce overexposed areas
False	Ignore overexposed areas and focus on matching the image brightness to the selected Auto Reference Value .
USB3 Vision: GenICam	ExposureAutoHighlightReduction
Type	Boolean
Video4Linux2	Highlight Reduction
VCD Property	VCDID_HighlightReduction\VCDElement_Value

5.3.5 Auto Exposure Limits

The *Auto Exposure Lower Limit* parameter determines the minimum possible value that can be set by the auto exposure algorithm.

Parameter	Auto Exposure Lower Limit
Minimum	50 μ s
Maximum	1 s
USB3 Vision: GenICam	ExposureAutoLowerLimit
Type	Float
Video4Linux2	Exposure Auto Lower Limit

The *Auto Exposure Upper Limit* parameter determines the maximum possible value that can be set by the auto exposure algorithm.

Parameter	Auto Exposure Upper Limit
Minimum	50 μ s
Maximum	1 s
USB3 Vision: GenICam	ExposureAutoUpperLimit
Type	Float
Video4Linux2	Exposure Auto Upper Limit
VCD Property	VCDID_Exposure\VCDElement_AutoMaxValue

If the *Auto Exposure Upper Limit Auto* parameter is enabled, the value of *Auto Exposure Upper Limit* is automatically kept at the maximum possible value for the current frame rate.

Parameter	Auto Exposure Upper Limit Auto
On	Select <i>Auto Exposure Upper Limit</i> automatically
Off	Let the user control <i>Auto Exposure Upper Limit</i>
USB3 Vision: GenICam	ExposureAutoUpperLimitAuto
Type	Enumeration
Video4Linux2	Exposure Auto Upper Limit Auto
VCD Property	VCDID_Exposure\VCDElement_AutoMaxValueAuto

5.3.6 Auto Gain Limits

The *Auto Gain Lower Limit* parameter determines the minimum possible value that can be set by the auto gain algorithm.

Parameter	Auto Gain Lower Limit
Minimum	0 dB
Maximum	42,14 dB
USB3 Vision: GenICam	GainAutoLowerLimit
Type	Float
Video4Linux2	Gain Auto Lower Limit

The *Auto Gain Upper Limit* parameter determines the maximum possible value that can be set by the auto gain algorithm.

Parameter	Auto Gain Upper Limit
Minimum	0 dB
Maximum	42,14 dB
USB3 Vision: GenICam	GainAutoUpperLimit
Type	Float
Video4Linux2	Gain Auto Upper Limit

5.4 Trigger

The trigger mode can be used to take images at very specific points in time which are specified by an electrical signal connected to the [TRIGGER_IN](#) pin of the I/O connector of the camera.

5.4.1 Trigger Mode

The *Trigger Mode* parameter enables the trigger mode.

Parameter	Trigger Mode
On	Enable Trigger Mode
True	
Off	Disable Trigger Mode
False	
USB3 Vision: GenICam	TriggerMode
Type	Enumeration
Video4Linux2	Trigger Mode
VCD Property	VCDID_Trigger\VCDElement_Value

5.4.2 Trigger Polarity

The *Trigger Polarity* parameter controls whether a trigger event is accepted on the rising or falling edge of the signal connected to the TRIGGER_IN line.

Parameter	Trigger Polarity
RisingEdge	Accept rising edge as trigger signal
True	
FallingEdge	Accept falling edge as trigger signal
False	
USB3 Vision: GenICam	TriggerActivation
Type	Enumeration
Video4Linux2	Trigger Polarity
VCD Property	VCDID_Trigger\VCDElement_Polarity

5.4.3 Software Trigger

The *Software Trigger* function can be used to simulate a trigger pulse, in turn causing one image to be exposed and delivered to the host computer.

Parameter	Software Trigger
Execute	Simulate one trigger pulse
USB3 Vision: GenICam	TriggerSoftware
Type	Command
Video4Linux2	Software Trigger
VCD Property	VCDID_Trigger\VCDElement_SoftwareTrigger

5.4.4 Trigger Burst Count

The *Trigger Burst Count* parameter allows the camera to be configured to take more than one image per trigger pulse. By default, this parameter is set to 1 so that exactly one image is acquired. The images are taken as rapidly as possible given current settings (i.e. as limited by the current exposure time and frame rate settings).

Parameter	Trigger Burst Count
Minimum	1
Maximum	65535
Default	1
USB3 Vision: GenICam	AcquisitionBurstFrameCount
Type	Integer
Video4Linux2	Trigger Burst Count
VCD Property	VCDID_Trigger\VCDElement_TriggerBurstCount

5.4.5 Trigger Source

The *Trigger Source* parameter allows the camera to be configured to only accept trigger signals from a specified source, e.g. only software trigger.

Parameter	Trigger Source
Any	Allow trigger signals from any source
Line1	Allow only hardware trigger
Software	Allow only software trigger
USB3 Vision: GenICam	TriggerSource
Type	Enumeration

5.4.6 Trigger Overlap

The *Trigger Overlap* feature gives information on when a new trigger pulse is accepted in the trigger -> exposure -> readout sequence.

Parameter	Trigger Overlap
Off	The next trigger pulse is only accepted once the previous frame has been read out from the sensor
Readout	The next trigger pulse is accepted during readout as long as the remaining readout time is shorter than the exposure time
USB3 Vision: GenICam	TriggerOverlap
Type	Enumeration
VCD Property	VCDID_Trigger\VCDElement_TriggerOverlap

5.4.7 Trigger Delay

The *Trigger Delay* parameter specifies a time for which the camera waits between receiving a trigger signal and starting the exposure of an image. Simulated trigger pulses generated through the *Software Trigger* function are not delayed by this parameter.

Parameter	Trigger Delay
Minimum	0 s
Maximum	1 s
USB3 Vision: GenICam	TriggerDelay
Type	Float
Video4Linux2	Trigger Delay
VCD Property	VCDID_Trigger\VCDElement_TriggerDelay

5.5 Trigger Timing Parameters

The 33U series camera series offers several options for dealing with bad trigger signals. By using the *Debounce Time*, *Denoise Time* and *Mask Time* parameters, the camera can be configured to ignore pulses on its [TRIGGER IN](#) line under certain conditions.

Useful values for these parameters are application-specific. They depend on the expected trigger frequency, the exposure time and assumptions about the input signal quality.

The default values for all these parameters is 0 μ s, assuming perfect signal quality.

5.5.1 Trigger Debounce Time

The *Trigger Debounce Time* parameter specifies the time for which the trigger input has to be low in order for the next trigger signal to be accepted.

Parameter	Trigger Debounce Time
Minimum	0 s
Maximum	1 s
Default	0 s
USB3 Vision: GenICam	TriggerDebouncer
Type	Float
Video4Linux2	Trigger Debounce Time (us)
VCD Property	VCDID_Trigger\VCDElement_TriggerDebouncer

5.5.2 Trigger Mask Time

The *Trigger Mask Time* parameter specifies the time for which trigger pulses are ignored after accepting a trigger signal.

Parameter	Trigger Mask Time
Minimum	0 s
Maximum	1 s
Default	0 s
USB3 Vision: GenICam	TriggerMask
Type	Float
Video4Linux2	Trigger Mask Time (us)
VCD Property	VCDID_Trigger\VCDElement_TriggerMask

5.5.3 Trigger Noise Suppression Time

The *Trigger Noise Suppression Time* parameter specifies the time for which trigger input has to be active in order to be accepted as a trigger signal.

Parameter	Trigger Noise Suppression Time
Minimum	0 s
Maximum	1 s
Default	0 s
USB3 Vision: GenICam	TriggerDenoise
Type	Float
Video4Linux2	Trigger Noise Suppression Time
VCD Property	VCDID_Trigger\VCDElement_TriggerDenoise

5.6 Digital I/O

The 33U series has one digital input and one digital output. The digital input can be used as a [Trigger](#) input but the current status can also be examined directly.

The digital output can be configured as a [Strobe](#) output to signal the exact moment when the image sensor is sensitive to light so that external light sources can be synchronized to its operation cycle.

5.6.1 General Purpose Input

The *General Purpose Input* parameter allows the current status of the [TRIGGER_IN](#) pin.

Parameter	General Purpose Input
True	TRIGGER_IN line status is low
1	
False	TRIGGER_IN line status is high
0	
USB3 Vision: GenICam	GPIIn
Type	Boolean
Video4Linux2	GPIN
VCD Property	VCDID_GPIO\VCDElement_GPIORead VCDID_GPIO\VCDElement_GPIOIn

5.6.2 General Purpose Output

The *General Purpose Output* parameter controls the status of the [STROBE_OUT](#) pin.

Parameter	General Purpose Output
True	Drive the STROBE_OUT line high
1	
False	Drive the STROBE_OUT line low
0	
USB3 Vision: GenICam	GPOut
Type	Boolean
Video4Linux2	GPOUT
VCD Property	VCDID_GPIO\VCDElement_GPIOWrite VCDID_GPIO\VCDElement_GPIOOut

5.7 Strobe

The strobe function controls the automatic generation of output pulses on the [STROBE_OUT](#) pin which is synchronized to the image sensor's exposure time.

5.7.1 Strobe Enable

The *Strobe Enable* parameter enables the automatic generation of strobe pulses.

Parameter	Strobe Enable
On	Strobe enabled
True	
Off	Strobe disabled
False	
USB3 Vision: GenICam	StrobeEnable
Type	Enumeration
Video4Linux2	Strobe Enable
VCD Property	VCDID_Strobe\VCDElement_Value

5.7.2 Strobe Polarity

The *Strobe Polarity* parameter can be used to invert the strobe pulse output.

Parameter	Strobe Polarity
ActiveHigh	The STROBE_OUT pin is logically high during the exposure time
True	
ActiveLow	The STROBE_OUT pin is logically low during the exposure time
False	
USB3 Vision: GenICam	StrobePolarity
Type	Enumeration
Video4Linux2	Strobe Polarity
VCD Property	VCDID_Strobe\VCDElement_StrobePolarity

5.7.3 Strobe Operation

The *Strobe Operation* parameter specifies how the length of the strobe pulses are controlled.

Parameter	Strobe Operation
Exposure	Output pulse duration is equal to the current exposure time
True	
USB3 Vision: GenICam	StrobeOperation
Type	Enumeration
Video4Linux2	Strobe Exposure
VCD Property	VCDID_Strobe\VCDElement_StrobeMode

5.8 White Balance

The DFK 33UR0234 color camera can perform white balance by digital multiplication of the appropriate raw pixel values.

5.8.1 Auto White Balance

DFK 33UR0234 can perform *Auto White Balance*. It can be enabled continuously when changes in lighting conditions are expected. Under controlled lighting conditions, however, one-time white balance calibration is the recommended approach.

To perform one-time white balance calibration, place a reference white sheet in front of the camera and set `BalanceWhiteAuto` to *Once*. The camera will then find the correct white balance settings for the current light conditions and keep them active until instructed otherwise.

Parameter	Auto White Balance
Continuous	Enable automatic white balance
True	
Once	
One Push	Enable automatic white balance until the color channels have been balanced once
Off	Disable automatic white balance
False	
USB3 Vision: GenICam	<code>BalanceWhiteAuto</code>
Type	Enumeration
Video4Linux2	<code>White Balance Component, Auto</code>
VCD Property	<code>VCDID_WhiteBalance\VCDElement_Auto</code> <code>VCDID_WhiteBalance\VCDElement_OnePush</code>

5.8.2 White Balance Mode

The default auto white balance algorithm is *Gray World*. It is selected by setting the *White Balance Mode* accordingly. The *Gray World* algorithm operates under the assumption that the average color of a scene is near gray and adjusts the white balance coefficients so the average color of the resulting image is gray as well. In the case where this assumption is wrong (e.g. the camera is pointing at a blue carpet), the auto white balance algorithm will select coefficients that do not result in a visually accurate image.

To avoid the problems posed by the *Gray World* algorithm, the *Temperature* mode can be used. This mode operates by trying to determine the color temperature of the light source.

Parameter	White Balance Mode
Gray World	Use the <i>Gray World</i> model
Temperature	Use the <i>Temperature</i> model
USB3 Vision: GenICam	BalanceWhiteMode
Type	Enumeration
Video4Linux2	Whitebalance Mode
VCD Property	VCDID_WhiteBalance \VCDElement_WhiteBalanceMode

To assist the automatic white balance temperature detection, *White Balance Auto Preset* can be used to limit the range of valid color temperatures.

Parameter	White Balance Auto Preset
Any	Allow any color temperature
Auto Warm White	Limit color temperature to approximately 2500-4000 K
Auto Cool White	Limit color temperature to approximately 4000-5800 K
Auto Daylight	Limit color temperature to approximately 5700-7500 K
Auto Deep Shade	Limit color temperature to approximately 7500-10000 K
USB3 Vision: GenICam	BalanceWhiteAutoPreset
Type	Enumeration
Video4Linux2	Whitebalance Auto Preset
VCD Property	VCDID_WhiteBalance \VCDElement_WhiteBalanceAutoPreset

5.8.3 Manual White Balance

If *Auto White Balance* is not enabled, the amplifiers for the red, green and blue channels can be controlled manually.

Parameter	White Balance Red
Minimum	0
Maximum	3.984375
Default	auto
USB3 Vision: GenICam	BalanceRatio[BalanceRatioSelector=Red]
Type	Float
Video4Linux2	White Balance Red Component
VCD Property	VCDID_WhiteBalance \VCDElement_WhiteBalanceRed

Parameter	White Balance Green
Minimum	0
Maximum	3.984375
Default	auto
USB3 Vision: GenICam	BalanceRatio[BalanceRatioSelector=Green]
Type	Float
Video4Linux2	White Balance Green Component
VCD Property	VCDID_WhiteBalance \VCDElement_WhiteBalanceGreen

Parameter	White Balance Blue
Minimum	0
Maximum	3.984375
Default	auto
USB3 Vision: GenICam	BalanceRatio[BalanceRatioSelector=Blue]
Video4Linux2	White Balance Blue Component
VCD Property	VCDID_WhiteBalance \VCDElement_WhiteBalanceBlue

If *White Balance Mode* is set to *Temperature*, the color temperature can be set directly. Additionally, a light source can be selected from a list of presets.

Parameter	White Balance Temperature
Minimum	2500 K
Maximum	10000 K
Default	auto
Increment	100
USB3 Vision: GenICam	BalanceWhiteTemperature
Type	Integer
Video4Linux2	White Balance Temperature
VCD Property	VCDID_WhiteBalance \VCDElement_WhiteBalanceTemperature

Parameter	White Balance Temperature Preset
Sodium-Vapor Lamp	2500 K
Warm Light	2700 K
Halogen Light	3000 K
Neutral White	3500 K
Cool White Fluorescent Light	4000 K
Cool White/Daylight (CFL)	5000 K
Daylight	6000 K
Cool White LED	7500 K
Blue Sky	10000 K
USB3 Vision: GenICam	BalanceWhiteTemperaturePreset
Type	Enumeration
Video4Linux2	Whitebalance Temperature Preset
VCD Property	VCDID_WhiteBalance \VCDElement_TemperaturePreset

5.9 Image Processing

5.9.1 Gamma

The 33U series cameras can perform gamma correction on the image data. If the pixel format of a color camera is set a YUV mode, gamma correction is applied to the Y channel. In bayer raw and RGB24 modes, all color channels are subject to the same gamma correction.

Parameter	Gamma
Minimum	0.01
Maximum	5.0
Default	1.0
USB3 Vision: GenICam	Gamma
Type	Float
Video4Linux2	Gamma
VCD Property	VCDID_Gamma\VCDElement_Value

5.9.2 Lookup Table

The 33U series allows the user to specify a lookup table (LUT) that can transform pixel values. This lookup table can be used to perform tasks like histogram equalization inside the camera.

If the pixel format of a color camera is set to one of the YUV modes, the lookup table is applied only to the Y channel. In bayer raw and RGB24 modes, all color channels are subject to the same lookup operation.

The lookup table has 257 16-bit entries. The upper 8 bits of the image data are used to select the appropriate entry in the lookup table, while the remaining bits are used to interpolate between the selected entry and one of its neighbors.

The *LUT Enable* feature enables the lookup table.

Parameter	LUT Enable
True	Enable lookup table operation
False	Disable lookup table operation
USB3 Vision: GenICam	LUTEnable
Type	Boolean

The lookup table values can be programmed using the *LUT Index* and *LUT Value* features.

Parameter	LUT Index
Minimum	0
Maximum	256
USB3 Vision: GenICam	LUTIndex
Type	Integer

Parameter	LUT Value
Minimum	0
Maximum	65535
USB3 Vision: GenICam	LUTValue
Type	Integer

The whole lookup table can be quickly reprogrammed through the *LUT Value All* feature.

Parameter	LUT Value All
Value	1028 bytes of memory containing 257 LUT entries. Each 16-bit LUT entry is aligned on a 32-bit boundary
USB3 Vision: GenICam	LUTValueAll
Type	Register

Important: Since gamma correction is implemented using the same hardware as the lookup table, gamma correction is disabled when the lookup table is enabled.

5.10 Color Processing

The DFK 33UR0234 color camera allows color adjustments with the *Hue* and *Saturation* parameters. These adjustments work with all output pixel formats.

Important: When a bayer raw pixel format is selected, *Hue* and *Saturation* still work. However, when at least one of them is enabled (set to non-default value), the resulting image is slightly blurred because of the way these parameters are implemented internally.

5.10.1 Hue

The *Hue* parameter controls the color angle of the output image.

Parameter	Hue
Minimum	-180
Maximum	180
Default	0
USB3 Vision: GenICam	Hue
Type	Float
Video4Linux2	Hue
VCD Property	VCDID_Hue\VCDElement_Value

5.10.2 Saturation

The *Saturation* parameter controls the color saturation of the output image.

Parameter	Saturation
Minimum	0
Maximum	255
Default	64
USB3 Vision: GenICam	Saturation
Type	Float
Video4Linux2	Saturation
VCD Property	VCDID_Saturation\VCDElement_Value

5.11 Region of Interest for Auto Functions

The 33U series cameras allow for the setting of a region of interest that is used while controlling the [Auto Exposure](#), [Auto Gain](#) and [Auto White Balance](#) functions.

5.11.1 Auto Functions ROI Enable

The *Auto Functions ROI Enable* parameter allows for the use of a region of interest for auto functions.

Parameter	Auto Functions ROI Enable
True	Auto functions only take a specified part of the image into account
False	Auto functions look at the whole image
USB3 Vision: GenICam	AutoFunctionsROIEnable
Type	Boolean
Video4Linux2	Auto Functions ROI Enable
VCD Property	VCDID_AutoRoi\VCDElement_Value

5.11.2 Auto Functions ROI Preset

The *Auto Functions ROI Preset* parameter lets the user select from a list of ROI presets.

Parameter	Auto Functions ROI Preset
Full Sensor	Select the full output image
Center 50%	Select a rectangular area in the center of the output image
Center 25%	Select a small rectangular area in the center of the output image
Bottom Half	Select the bottom half of the output image
Top Half	Select the top half of the output image
Custom Rectangle	Select a custom rectangle for fine-grained control
USB3 Vision: GenICam	AutoFunctionsROI_Preset
Type	Enumeration
Video4Linux2	Auto Functions ROI Preset
VCD Property	VCDID_AutoRoi\VCDElement_AutoRoiPreset

5.11.3 Auto Functions ROI Custom Rectangle

When *Auto Functions ROI Preset* is set to *Custom Rectangle*, the user can manually set the position and size of the region of interest. The coordinates are relative to the origin of the current video format as specified by [Partial Scan Offset](#).

Parameter	Auto Functions ROI Left
Minimum	0
Maximum	2576
Increment	2
USB3 Vision: GenICam	AutoFunctionsROILeft
Type	Integer
Video4Linux2	Auto Functions ROI Left
VCD Property	VCDID_AutoRoi \VCDElement_AutoRoiLeftRelative

Parameter	Auto Functions ROI Top
Minimum	0
Maximum	2032
Increment	2
USB3 Vision: GenICam	AutoFunctionsROITop
Type	Integer
Video4Linux2	Auto Functions ROI Top
VCD Property	VCDID_AutoRoi \VCDElement_AutoRoiTopRelative

Parameter	Auto Functions ROI Width
Minimum	16
Maximum	2592
Increment	2
USB3 Vision: GenICam	AutoFunctionsROIWidth
Type	Integer
Video4Linux2	Auto Functions ROI Width
VCD Property	VCDID_AutoRoi \VCDElement_AutoRoiWidthRelative

Parameter	Auto Functions ROI Height
Minimum	16
Maximum	2048
Increment	2
USB3 Vision: GenICam	AutoFunctionsROIHeight
Type	Integer
Video4Linux2	Auto Functions ROI Height
VCD Property	VCDID_AutoRoi \VCDElement_AutoRoiHeightRelative

5.12 User Sets

The 33U series cameras can store their complete configuration into built-in non-volatile memory. The camera configuration can be saved into and restored from one of two available memory slots upon user's request. Additionally, the camera can be configured to load one of the user's camera configurations at startup.

5.12.1 User Set Selector

The *User Set Selector* parameter selects the memory slot on which consecutive load and save commands are executed.

Parameter	User Set Selector
UserSet1	First of the two memory slots for user configurations
UserSet2	Second of the two memory slots for user configurations
Default	A special memory slot that always contains the camera's factory default configuration. It cannot be overwritten
USB3 Vision: GenICam	UserSetSelector
Type	Enumeration

5.12.2 Load User Set

By using the *Load User Set* command, the user can restore the camera configuration from the memory slot selected by *User Set Selector*.

Parameter	Load User Set
Execute	Restore the camera configuration from the memory slot specified by <i>User Set Selector</i>
USB3 Vision: GenICam	UserSetLoad
Type	Command

5.12.3 Save User Set

By using the *Save User Set* command, the user can save the camera configuration into the memory slot selected by *User Set Selector*.

Parameter	Save User Set
Execute	Save the current camera configuration into the memory slot specified by <i>User Set Selector</i>
USB3 Vision: GenICam	UserSetSave
Type	Command

5.12.4 Default User Set

The *Default User Set* parameter controls the camera's startup behavior. It selects which memory slot is used for device initialization when the camera is powered up.

Parameter	Default User Set
UserSet1	Load configuration from the first memory slot
UserSet2	Load configuration from the second memory slot
Default	Load factory default configuration
USB3 Vision: GenICam	UserSetDefault
Type	Enumeration

5.13 Timestamp Control

33U series cameras run an internal timestamp clock. The clock starts at zero when the camera is powered up.

The source of the timestamp clock has a frequency tolerance of ± 50 ppm.

All image buffers sent by the camera have a timestamp attached to them.

Notification for asynchronous [Events](#) also contain a timestamp value.

5.13.1 Timestamp Latch

The *Timestamp Latch* command copies the current value of the camera's timestamp counter into the [Timestamp Latch Value](#) so that it can be read later.

Parameter	Timestamp Latch
Execute	Copies the current value of the camera's timestamp into Timestamp Latch Value .
USB3 Vision: GenICam	TimestampLatch
Type	Command

5.13.2 Timestamp Latch Value

The *Timestamp Latch Value* feature contains the value of camera's timestamp counter at the time of the previous execution of the [Timestamp Latch](#) command.

Parameter	Timestamp Latch Value
USB3 Vision: GenICam	TimestampLatchValue
Type	Integer
Unit	µs

5.13.3 Timestamp Reset

The *Timestamp Reset* command resets the camera's timestamp counter to start from zero.

Parameter	Timestamp Reset
Execute	Resets the camera's timestamp counter.
USB3 Vision: GenICam	TimestampReset
Type	Command

5.14 Events

33U series devices can send asynchronous event packets, notifying the application about certain events during device operation.

To enable a specific event, select the event to enable in [Event Selector](#) and then set [Event Notification](#) to *On*.

The way to receive the event notifications depends on the used camera SDK. In most cases, a notification handler has to be registered on the feature named after the event, e.g. *EventTest* or *EventExposureEnd*. Additional event data can often be queried via additional features with a derived name, e.g. *EventTestTimestamp* or *EventExposureEndFrameID*.

5.14.1 Event Selector

The *Event Selector* parameter selects an event to configure.

Parameter	Event Selector
ExposureEnd	Selects the ExposureEnd event
FrameTriggerMissed	Selects the FrameTriggerMissed event
Line1FallingEdge	Selects the Line1FallingEdge event
Line1RisingEdge	Selects the Line1RisingEdge event
Test	Selects the Test event
USB3 Vision: GenICam	EventSelector
Type	Enumeration

5.14.2 Event Notification

The *Event Notification* parameter enables or disables the event selected by [Event Selector](#).

Parameter	Event Notification
On	Enables notifications for the selected event
Off	Disables notifications for the selected event
USB3 Vision: GenICam	EventNotification
Type	Enumeration

5.14.3 Event Exposure End

The *Event Exposure End* feature is notified when the camera completes the exposure of an image.

It can be useful to synchronize camera exposure with real-world events, e.g. moving parts in front of the camera.

The value of this feature has no meaning and should not be read.

Parameter	Event Exposure End
USB3 Vision: GenICam	EventExposureEnd
Type	Integer

The *Event Exposure End Timestamp* parameter identifies the point in time when the current exposure end event occurred.

Please refer to the documentation of your camera SDK on how to safely read the timestamp associated with the current event when a notification is received.

Parameter	Event Exposure End Timestamp
USB3 Vision: GenICam	EventExposureEndTimestamp
Type	Integer

The *Event Exposure End Frame ID* parameter the frame number of the frame whose exposure was completed.

Please refer to the documentation of your camera SDK on how to safely read the timestamp associated with the current event when a notification is received.

Parameter	Event Exposure End Frame ID
USB3 Vision: GenICam	EventExposureEndFrameID
Type	Integer

5.14.4 Event Frame Trigger Missed

The *Event Frame Trigger Missed* feature is notified when the camera receives a trigger pulse, but the sensor was not in a state where a new exposure could be started.

The value of this feature has no meaning and should not be read.

Parameter	Event Frame Trigger Missed
USB3 Vision: GenICam	EventFrameTriggerMissed
Type	Integer

The *Event Frame Trigger Missed Timestamp* parameter identifies the point in time when the current frame trigger missed event occurred.

Please refer to the documentation of your camera SDK on how to safely read the timestamp associated with the current event when a notification is received.

Parameter	Event Frame Trigger Missed Timestamp
USB3 Vision: GenICam	EventFrameTriggerMissedTimestamp
Type	Integer

5.14.5 Event Line1 Falling Edge

The *Event Line1 Falling Edge* feature is notified when the input on Line1 changes from high to low.

The value of this feature has no meaning and should not be read.

Parameter	Event Line1 Falling Edge
USB3 Vision: GenICam	EventLine1FallingEdge
Type	Integer

The *Event Line1 Falling Edge Timestamp* parameter identifies the point in time when the current line1 falling edge event occurred.

Please refer to the documentation of your camera SDK on how to safely read the timestamp associated with the current event when a notification is received.

Parameter	Event Line1 Falling Edge Timestamp
USB3 Vision: GenICam	EventLine1FallingEdgeTimestamp
Type	Integer

5.14.6 Event Line1 Rising Edge

The *Event Line1 Rising Edge* feature is notified when the input on Line1 changes from high to low.

The value of this feature has no meaning and should not be read.

Parameter	Event Line1 Rising Edge
USB3 Vision: GenICam	EventLine1RisingEdge
Type	Integer

The *Event Line1 Rising Edge Timestamp* parameter identifies the point in time when the current line1 rising edge event occurred.

Please refer to the documentation of your camera SDK on how to safely read the timestamp associated with the current event when a notification is received.

Parameter	Event Line1 Rising Edge Timestamp
USB3 Vision: GenICam	EventLine1RisingEdgeTimestamp
Type	Integer

5.14.7 Event Test

The *Event Test* feature is notified when a test event occurs.

To generate a test event, use the *Test Event Generate* command.

The value of this feature has no meaning and should not be read.

Parameter	Event Test
USB3 Vision: GenICam	EventTest
Type	Integer

The *Event Test Timestamp* parameter identifies the point in time when the current test event occurred.

Please refer to the documentation of your camera SDK on how to safely read the timestamp associated with the current event when a notification is received.

Parameter	Event Test Timestamp
USB3 Vision: GenICam	EventTestTimestamp
Type	Integer

The *Test Event Generate* command can be used to generate a test event.

Parameter	Test Event Generate
Execute	Generate one test event
USB3 Vision: GenICam	TestEventGenerate
Type	Command

5.15 Bandwidth Control

When using multiple 33U series devices connected to the same host controller, the data rate has to be considered to allow consistent operation.

To limit the bandwidth of a camera, set [Device Link Throughput Limit Mode](#) to On, and set [Device Link Throughput Limit](#) to the desired maximum data rate.

5.15.1 Device Link Throughput Limit Mode

The *Device Link Throughput Limit Mode* parameter enables or disables the effect of [Device Link Throughput Limit](#).

If set, the camera's internal frame rate is automatically reduced to fit into the available bandwidth.



Parameter	Device Link Throughput Limit Mode
Off	The bandwidth the device uses for streaming is unlimited.
On	The maximum bandwidth the device uses for streaming is defined by Device Link Throughput Limit .
USB3 Vision: GenICam	DeviceLinkThroughputLimitMode
Type	Enumeration

5.15.2 Device Link Throughput Limit

The *Device Link Throughput Limit* parameter defines the maximum bandwidth used by the device to stream data.

[Device Link Throughput Limit Mode](#) must be set to `On` for *Device Link Throughput Limit* to have an effect.

Parameter	Device Link Throughput Limit
Minimum	1000000 Mbps
Maximum	4000000000 Mbps
USB3 Vision: GenICam	DeviceLinkThroughputLimit
Type	Integer



6 Revision History

Date	Version	Description
2023/07/19		Updated environmental section in quick facts chapter.
2023/11/08	1540	Fixed erroneously limited gain calculation and enhance gain range.
2024/01/09	Firmware 1554	Add EventExposureEnd, EventFrameTriggerMissed, EventLine1RisingEdge, EventLine1FallingEdge features
2024/11/13	Firmware 1732	Add DeviceLinkThroughputLimit feature



DFK 33UR0234 Technical Reference Manual

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